

Chapter 4

Intelligent Resource Allocation and Optimization for Industrial Robotics Using AI and Blockchain

Tarun Kumar Vashishth

 <https://orcid.org/0000-0001-9916-9575>

IIMT University, India

Vikas Sharma

 <https://orcid.org/0000-0001-8173-4548>

IIMT University, India


Kewal Krishan Sharma

IIMT University, India

Bhupendra Kumar

IIMT University, India

Sachin Chaudhary

 <https://orcid.org/0000-0002-8415-0043>

IIMT University, India

Rajneesh Panwar

IIMT University, India

ABSTRACT

This chapter focuses on the application of intelligent resource allocation and optimization techniques for industrial robotics systems using the synergistic integration of artificial intelligence (AI) and blockchain technologies. Efficient resource allocation is crucial for maximizing the performance and productivity of industrial robotics, and AI-based approaches offer the ability to dynamically allocate resources based on real-time data and system requirements. Additionally, blockchain technology provides a decentralized and secure platform for recording and verifying resource allocation transactions, ensuring transparency and trust in the allocation process. The chapter explores various AI algorithms and models that can be employed for resource allocation and optimization in industrial robotics, including machine learning, evolutionary algorithms, and reinforcement learning. Furthermore, the chapter investigates how blockchain technology can enhance resource allocation and optimization by providing a distributed ledger for recording and verifying resource transactions.

DOI: 10.4018/979-8-3693-0659-8.ch004

1. INTRODUCTION TO INDUSTRIAL ROBOTICS

Industrial robotics represents a transformative force in manufacturing and automation. Over the years, these sophisticated machines have evolved from simple mechanical arms to highly advanced systems capable of intricate tasks. This introduction serves as a gateway to understanding the world of industrial robotics, its historical evolution, current applications, and the profound impact it has on industries worldwide. As we delve into the depths of industrial robotics, we will explore their key components, working principles, and the pivotal role they play in optimizing production processes and enhancing efficiency. Moreover, we will discuss the latest trends and future prospects in the field, emphasizing the continuous innovation that drives this fascinating industry forward. So, let's embark on a journey to unravel the fascinating realm of industrial robotics.

2. SIGNIFICANCE OF RESOURCE ALLOCATION AND OPTIMIZATION IN INDUSTRIAL ROBOTICS

Efficient resource allocation and optimization are critical components of modern industrial robotics systems. In the rapidly evolving landscape of manufacturing and automation, these processes hold significant importance for several key reasons:

- i. **Enhanced Efficiency:** Proper resource allocation ensures that industrial robots are used optimally, reducing downtime and increasing overall productivity. This efficiency is vital in meeting production targets and maintaining competitiveness in the market.
- ii. **Cost Savings:** Optimized resource allocation can lead to cost savings by reducing unnecessary energy consumption, wear and tear on equipment, and the need for human intervention. This can have a direct impact on a company's bottom line.
- iii. **Improved Quality:** By allocating resources effectively, industrial robots can consistently produce high-quality products, reducing defects and rework. This is crucial in industries where product quality is paramount, such as automotive and electronics manufacturing.
- iv. **Resource Scalability:** As production demands fluctuate, flexible resource allocation allows for easy scalability. Industrial robots can adapt to changes in production volume, ensuring that resources are neither overutilized nor underutilized.
- v. **Data-Driven Decision Making:** AI and blockchain technologies enable data collection and analysis on a granular level. This data can be used to make informed decisions about resource allocation and optimization, leading to continuous process improvement.
- vi. **Enhanced Safety:** Efficient resource allocation can also improve workplace safety. Robots can be allocated to handle dangerous or repetitive tasks, reducing the risk of accidents and injuries to human workers.
- vii. **Sustainability:** Optimized resource allocation can contribute to sustainability goals by minimizing energy consumption and waste. This aligns with the growing focus on environmentally friendly manufacturing practices.
- viii. **Competitive Advantage:** Companies that excel in resource allocation and optimization are often more competitive in their respective industries. They can offer better prices, shorter lead times, and higher quality products, attracting more customers.

27 more pages are available in the full version of this document, which may be purchased using the "Add to Cart" button on the publisher's webpage:
www.igi-global.com/chapter/intelligent-resource-allocation-and-optimization-for-industrial-robotics-using-ai-and-blockchain/336076

Related Content

Chatterbox Challenge as a Test-Bed for Synthetic Emotions

Jordi Vallverdú, Huma Shahand David Casacuberta (2010). *International Journal of Synthetic Emotions* (pp. 12-37).

www.irma-international.org/article/chatterbox-challenge-test-bed-synthetic/46131

FPGA-Based Object Detection and Motion Tracking in Micro- and Nanorobotics

Claas Diederichsand Sergej Fatikow (2013). *International Journal of Intelligent Mechatronics and Robotics* (pp. 27-37).

www.irma-international.org/article/fpga-based-object-detection-and-motion-tracking-in-micro--and-nanorobotics/87479

Dual Robot Control for Part Handling Services with Human Interaction

Theodor Borangiu, Florin Daniel Antonand Silvia Anton (2012). *Service Robots and Robotics: Design and Application* (pp. 338-356).

www.irma-international.org/chapter/dual-robot-control-part-handling/64672

Cloud Computing Principles for Optimizing Robot Task Offloading Processes

U. Rahamathunnisa, K. Sudhakar, Tamilarasi K. Murugan, Thivaharan S., Rajkumar M.and S. Boopathi (2023). *AI-Enabled Social Robotics in Human Care Services* (pp. 188-211).

www.irma-international.org/chapter/cloud-computing-principles-for-optimizing-robot-task-offloading-processes/322520

Synergistic Swarm: Multi-Robot Systems in Healthcare

Jaspreet Kaur (2024). *Modeling, Simulation, and Control of AI Robotics and Autonomous Systems* (pp. 166-179).

www.irma-international.org/chapter/synergistic-swarm/348040